

Pessimism is Great for Machine Learning!

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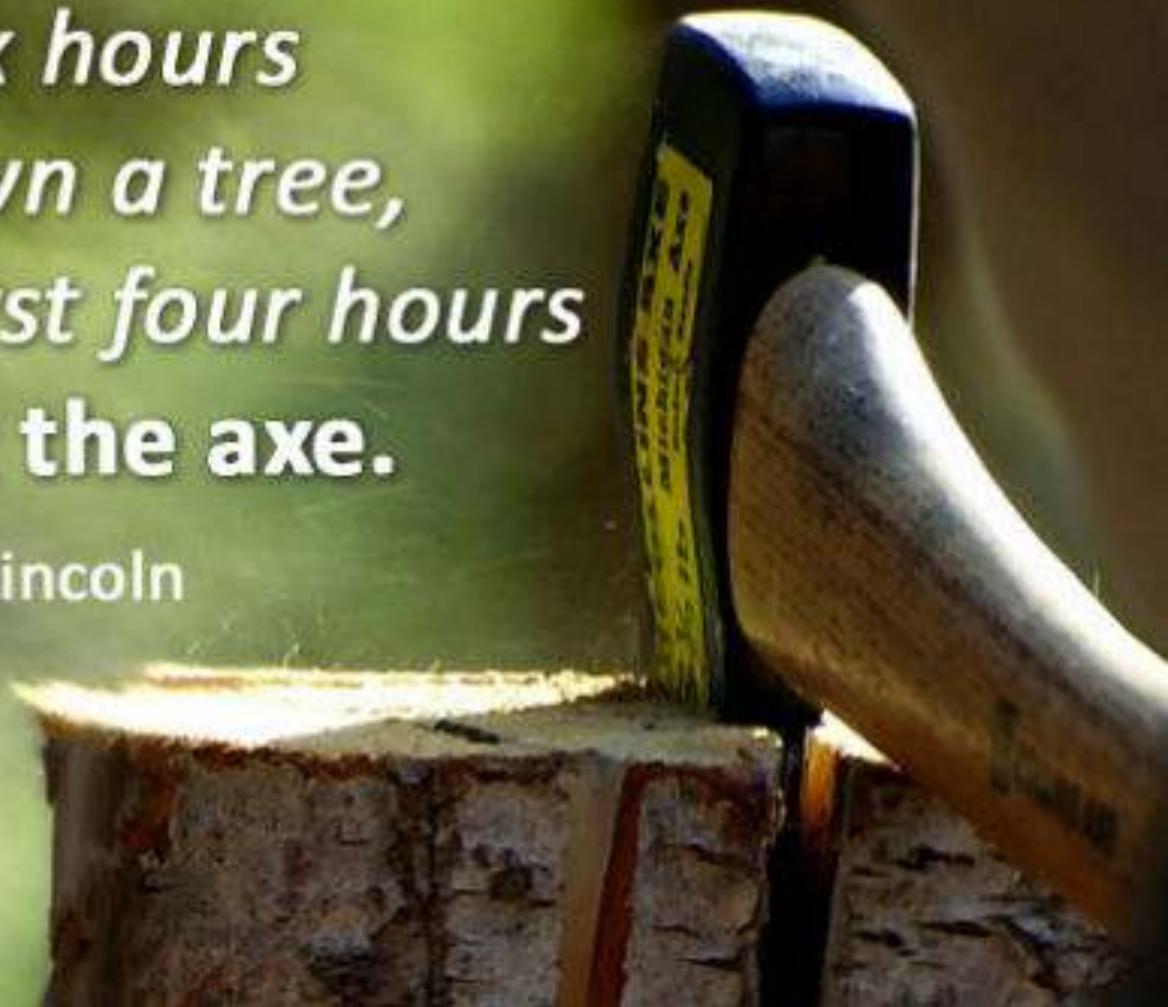


This project supports the PhD thesis
work of Anqi Liu (aliu33@uic.edu)



*If I had six hours
to chop down a tree,
I'd spend the first four hours
sharpening the axe.*

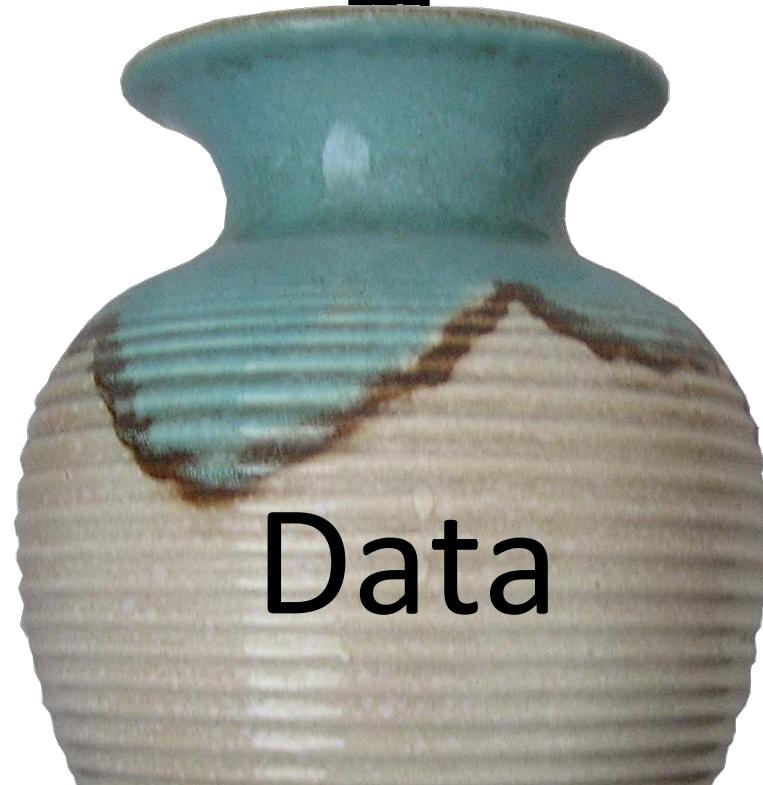
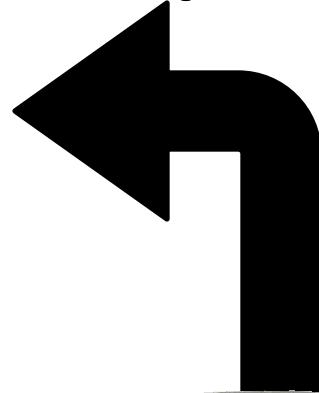
~ Abraham Lincoln



Training



M samples



Sample dist.
 $\tilde{P}(x, y)$

Data

Training



Testing

Prediction: $\hat{y}(x)$



Loss: $\text{loss}(\hat{y}, y)$



Sample dist.
 $\tilde{P}(x, y)$

Data

Testing

Prediction: $\hat{y}(x)$



Loss: $\text{loss}(\hat{y}, y)$

Expected Loss:
 $E_P[\text{loss}(\hat{y}(X), Y)]$

Sample dist.

$$\tilde{P}(x, y)$$



True dist.

$$P(x, y)$$

	Dog	Cat	Car
Dog	0	1	1
Cat	1	0	1
Car	1	1	0

	Dog	Cat	Car
Dog	0	1	5
Cat	1	0	5
Car	5	5	0

Empirical Risk Minimization

Minimize approximate loss on
exact training data



Adversarial Risk Minimization

Minimize exact loss on
approximate training data

		\hat{y}	v
		Dog	Cat
\hat{y}	Dog	0	1
\hat{y}	Cat	1	0
\hat{y}	Car	5	5

Find equilibrium \hat{P}, \hat{v}

Empirical Risk Minimization

Minimize approximate loss on
exact training data

Sometimes equivalent (log loss)

Pessimism is safer/better in general



Adversarial Risk Minimization

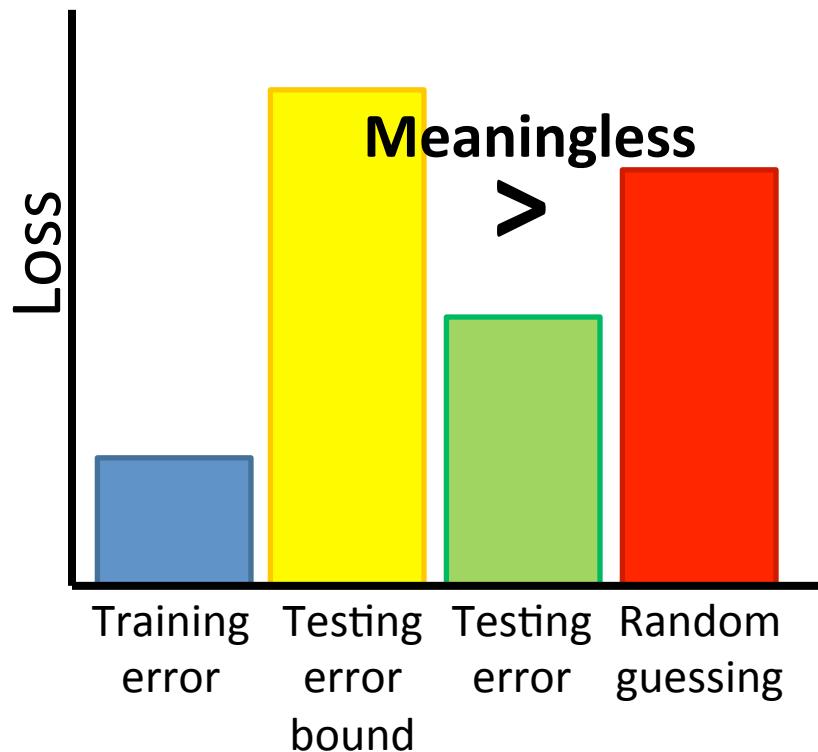
Minimize exact loss on
approximate training data

\hat{y}	Dog	Cat	Car
Dog	$0+\Psi_{\text{dog}}$	$1+\Psi_{\text{cat}}$	$5+\Psi_{\text{car}}$
Cat	$1+\Psi_{\text{dog}}$	$0+\Psi_{\text{cat}}$	$5+\Psi_{\text{car}}$
Car	$5+\Psi_{\text{dog}}$	$5+\Psi_{\text{cat}}$	$0+\Psi_{\text{car}}$

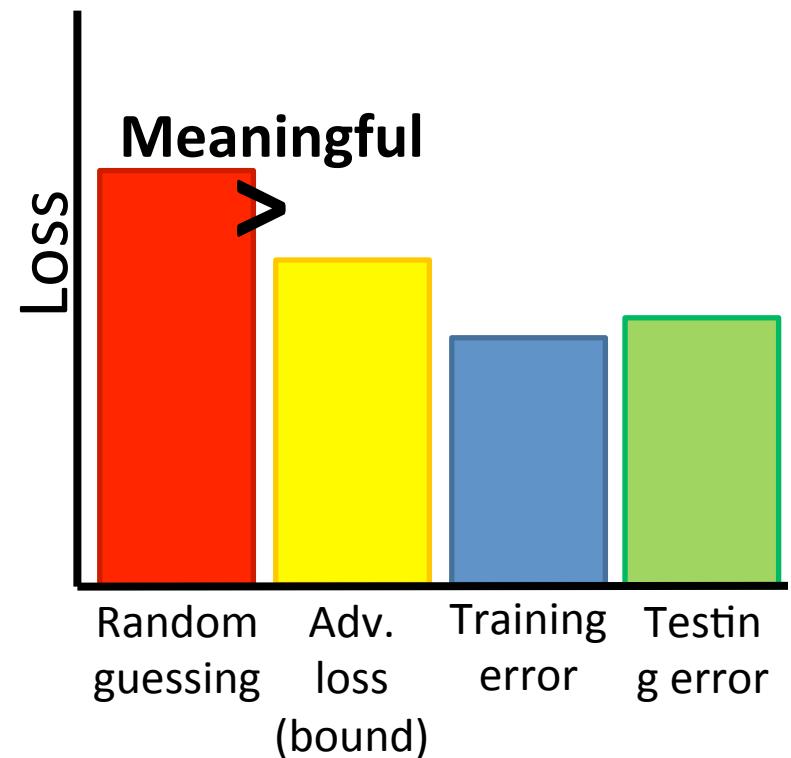
Find equilibrium \hat{P}, \hat{P}
 $\Psi_{\text{dog}} = \mathbf{w}_{\text{dog}} \cdot \mathbf{f}(\mathbf{x})$

Meaningful Generalization Bounds

Empirical Risk Minimization

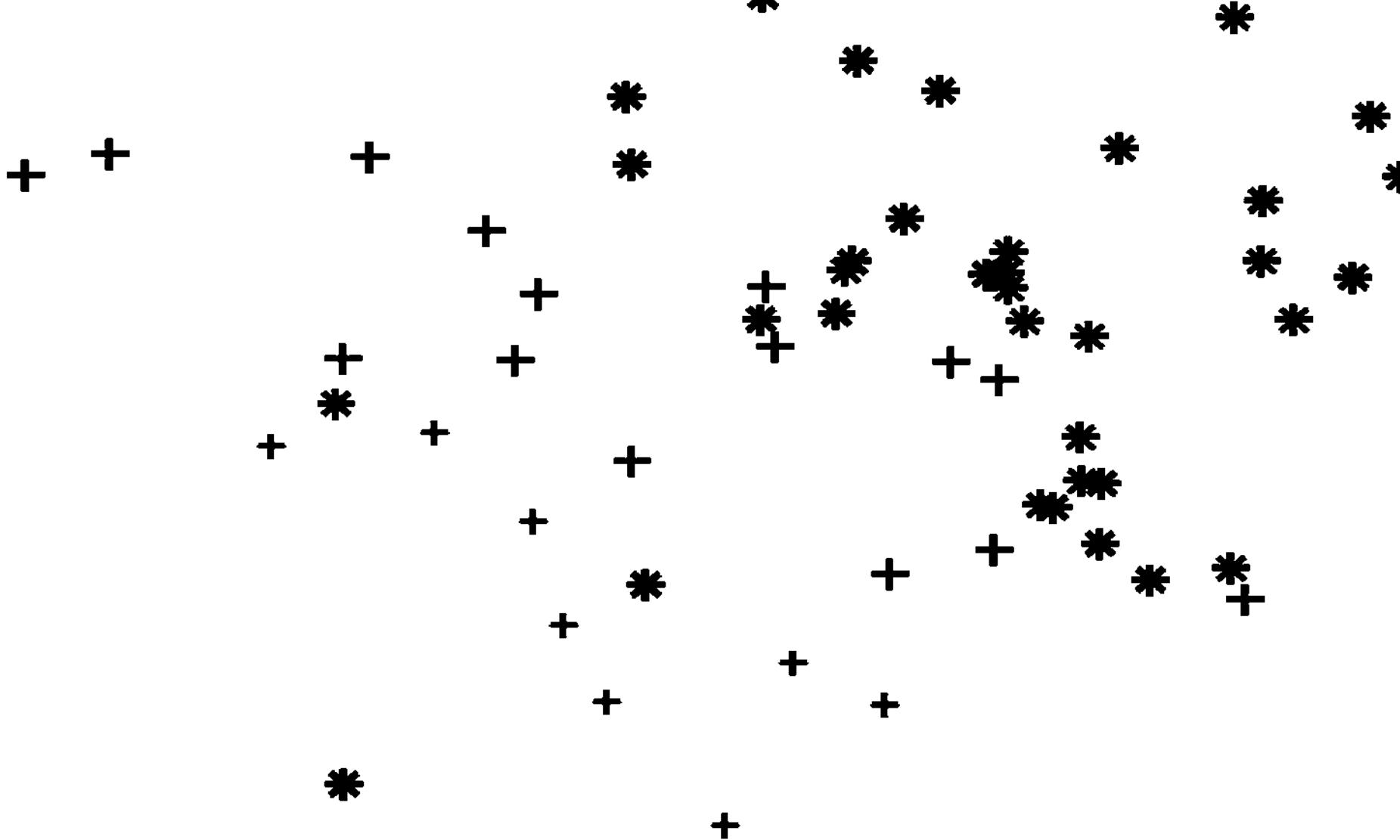


Adversarial Risk Minimization



Especially important when training and testing distributions differ (covariate shift) [Liu & Ziebart 2014, Liu et al. 2015, Chen et al. 2016]

Active Learning



Wrong, but certain
about datapoints
over here

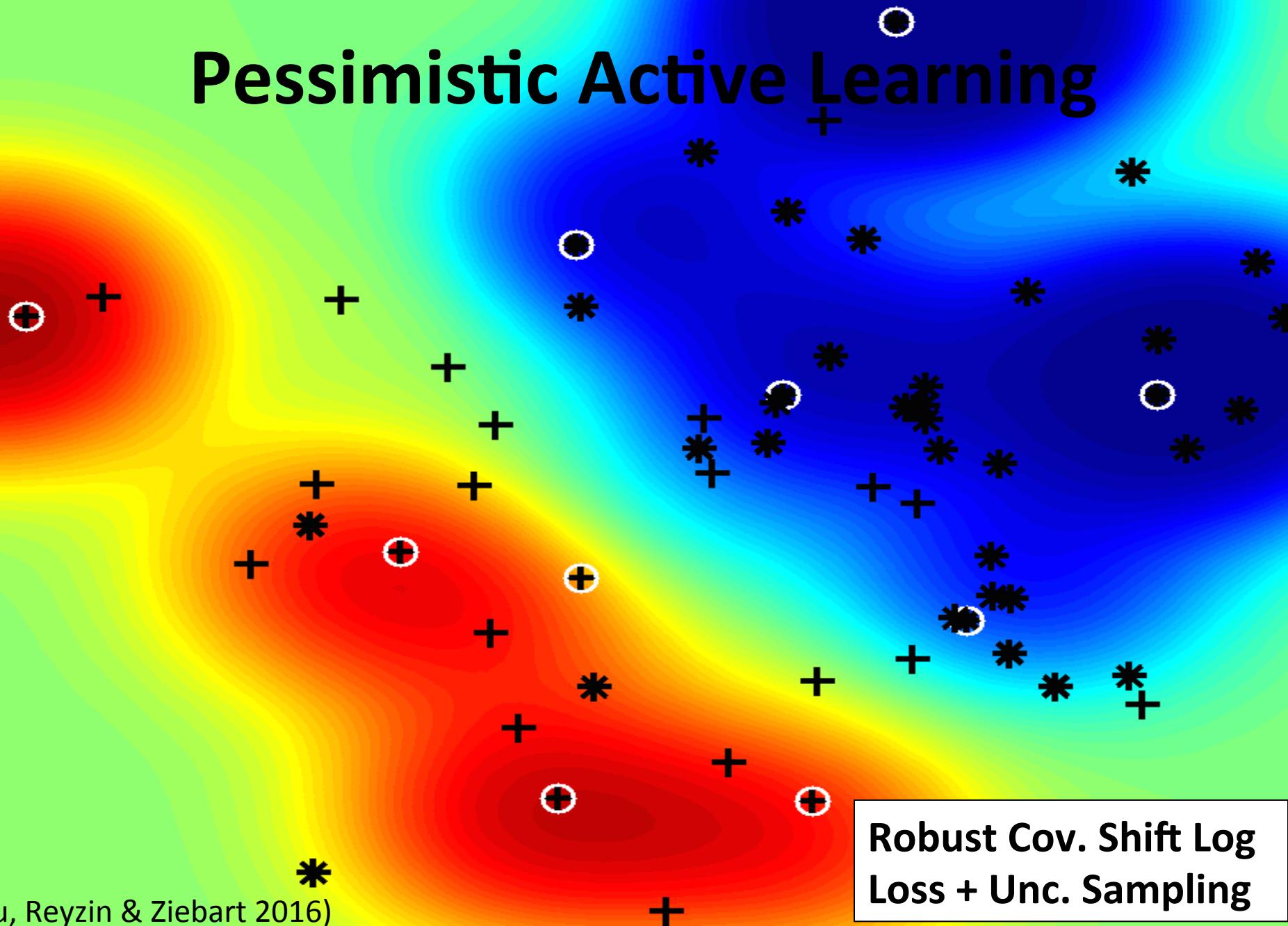
ERM Active Learning

Labels all datapoints here
before correcting the model

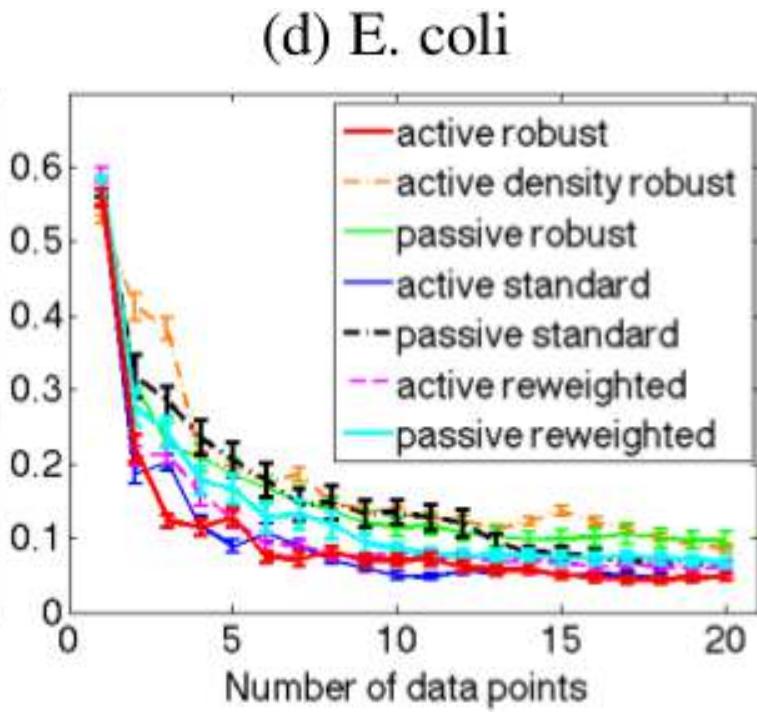
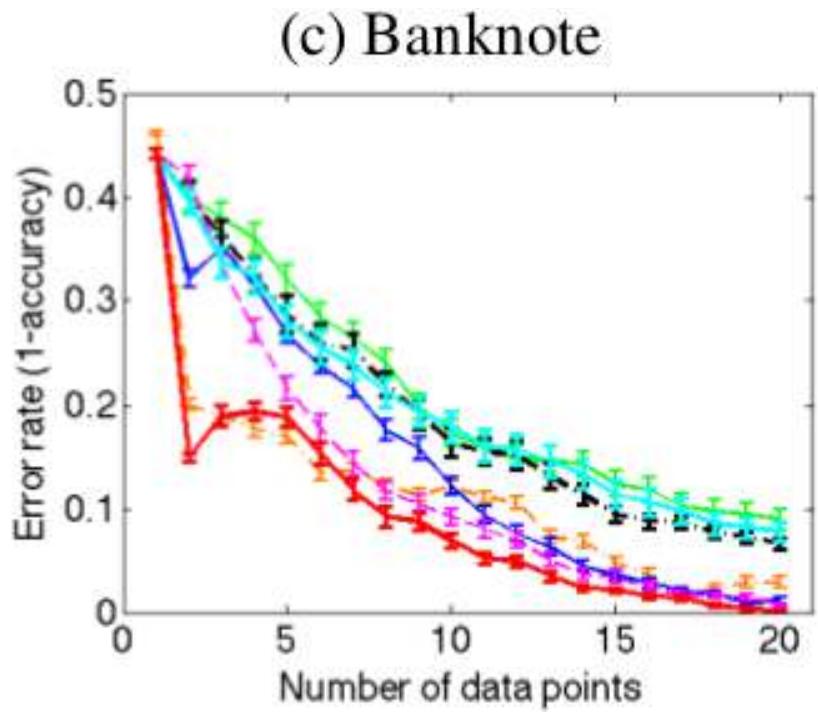
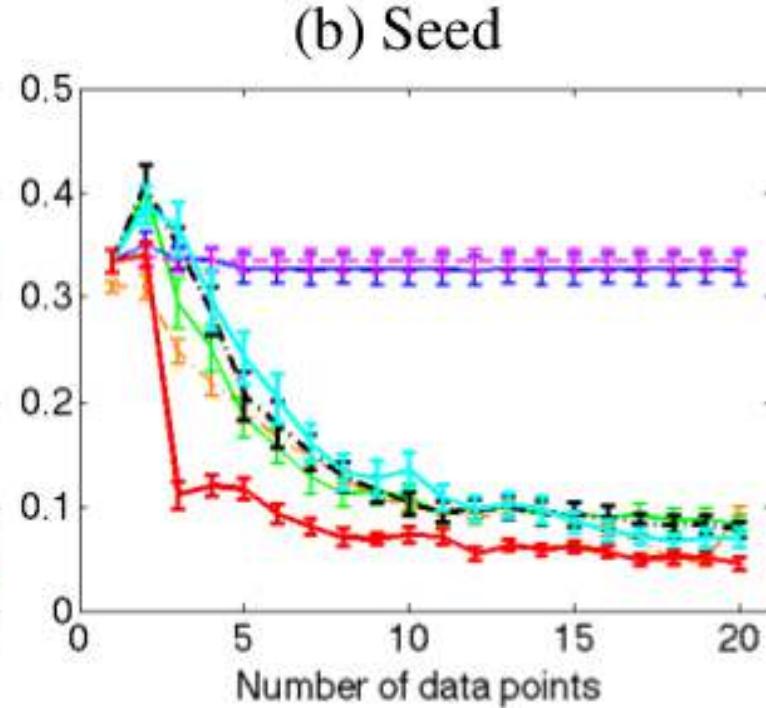
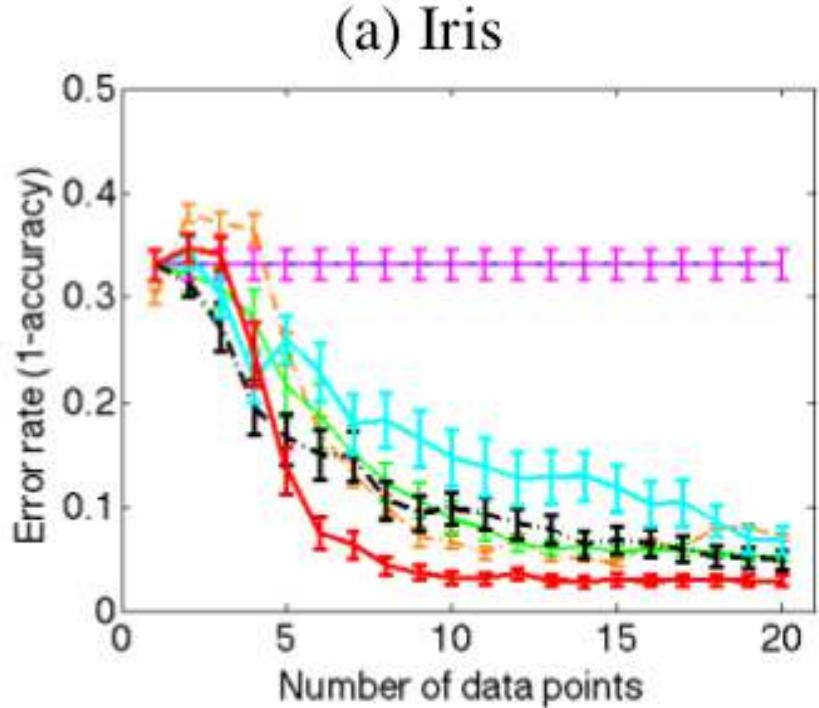
Good performance
on labeled data

Logistic Regression +
Uncertainty Sampling

Pessimistic Active Learning

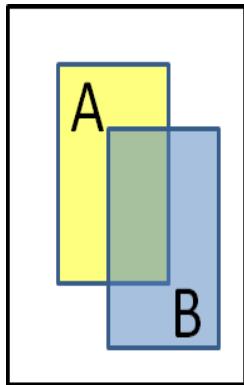


Robust Cov. Shift Log
Loss + Unc. Sampling



Pessimism Better for Specialized Losses

Object localization: performance based on overlap



Thresholded overlap:

Incorrect if overlap $< 70\%$

Correct if overlap $\geq 70\%$

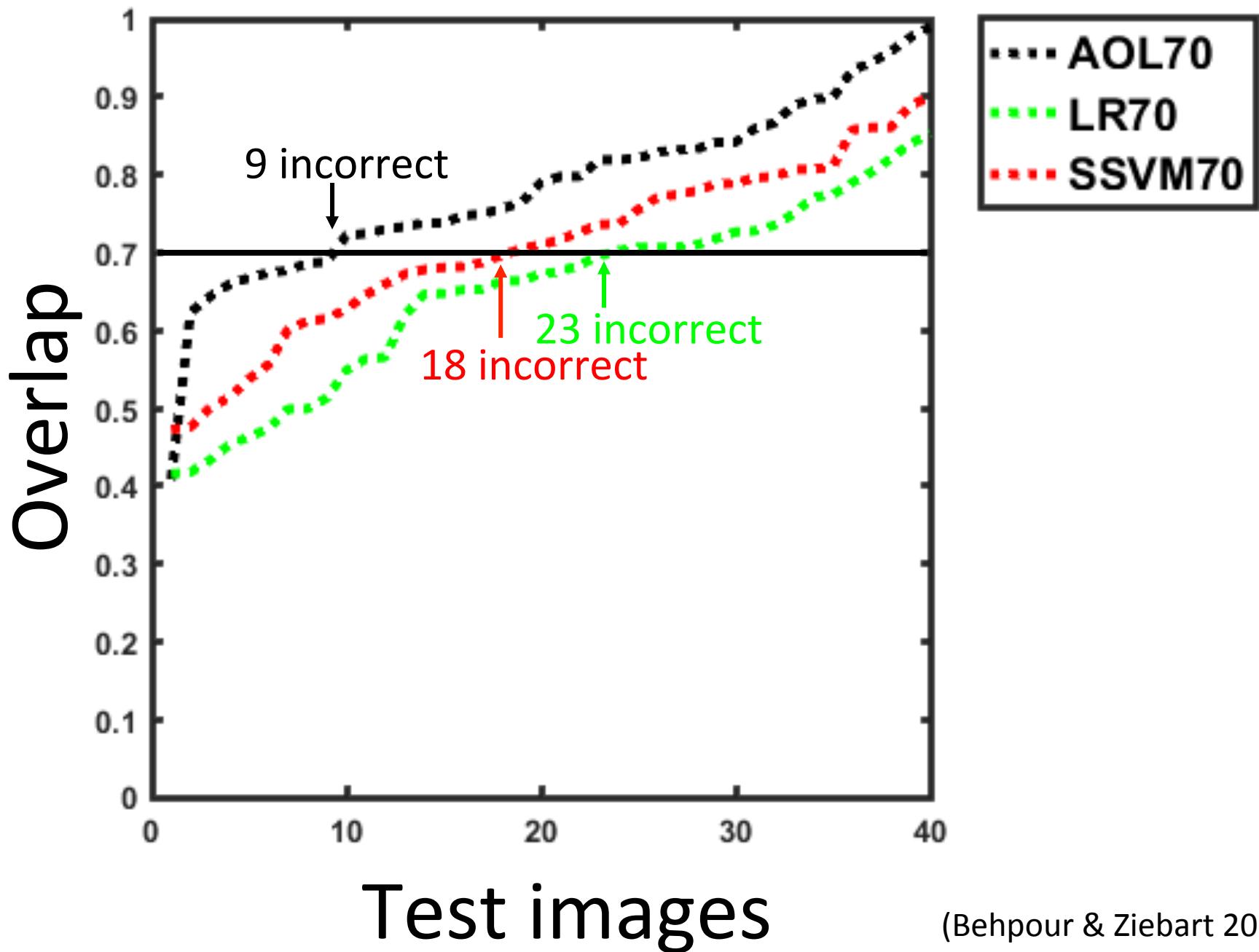
Methods: Bayes act under logistic regression (LR) _
Hinge loss approximation (SSVM)
Adversarial object localization (AOL)

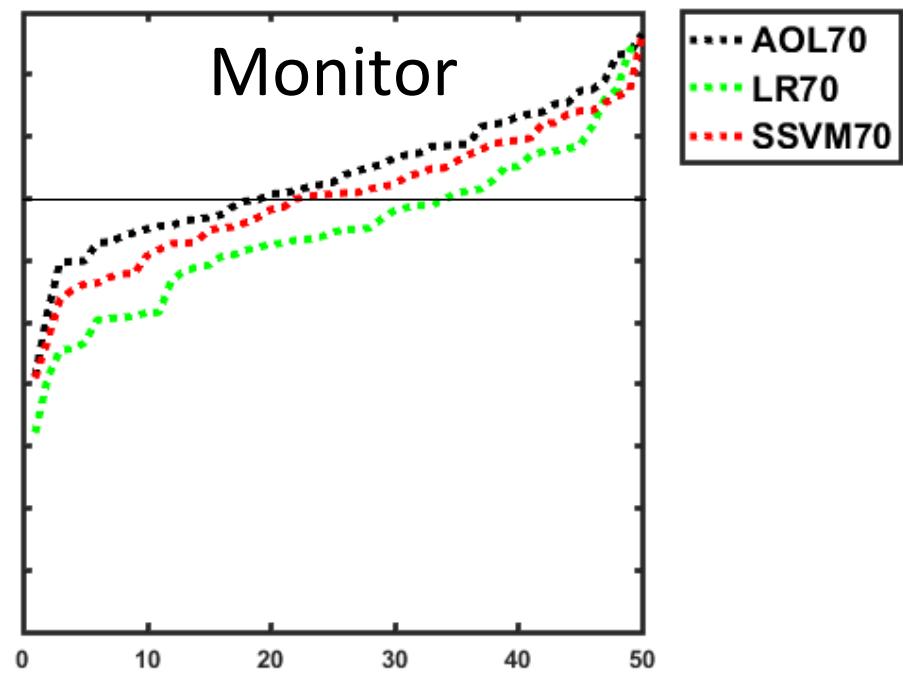
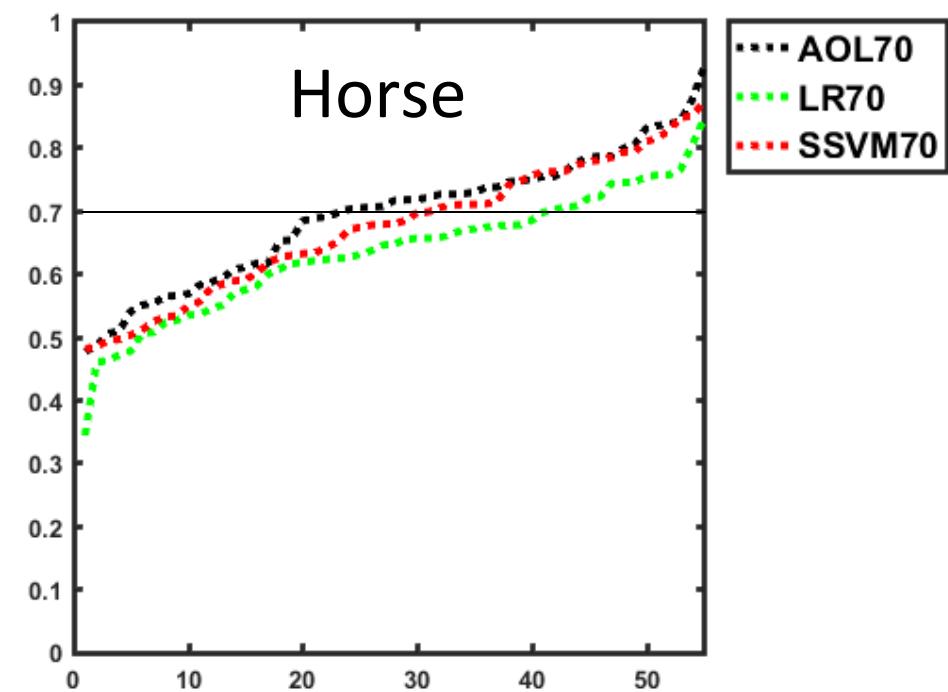
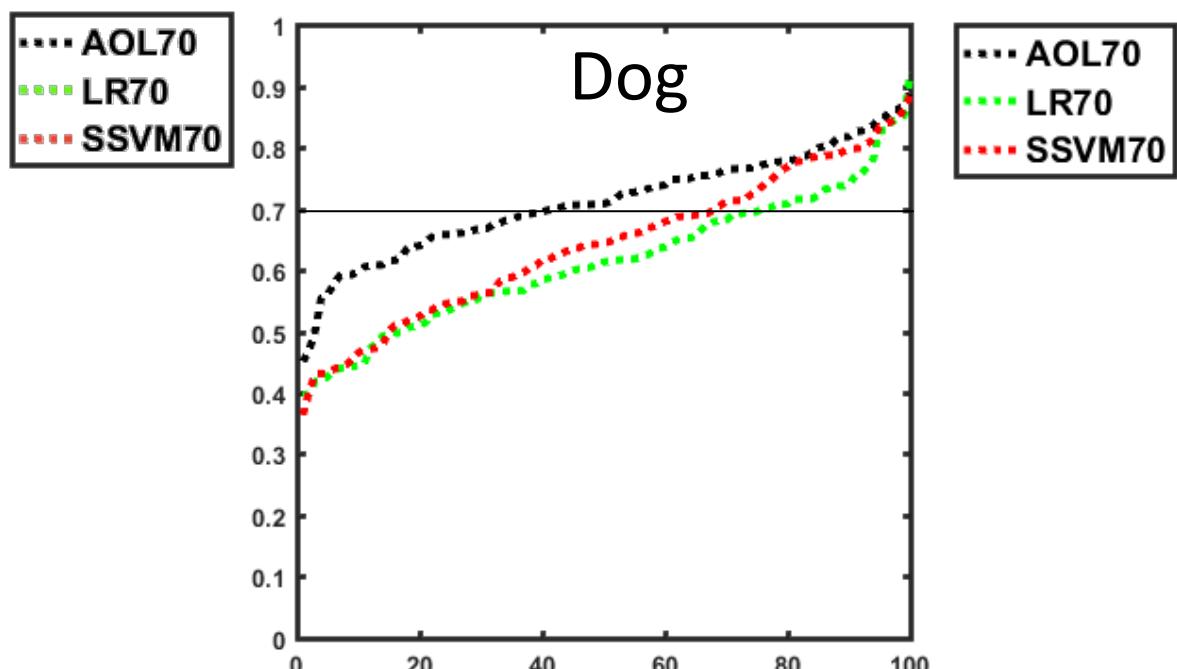
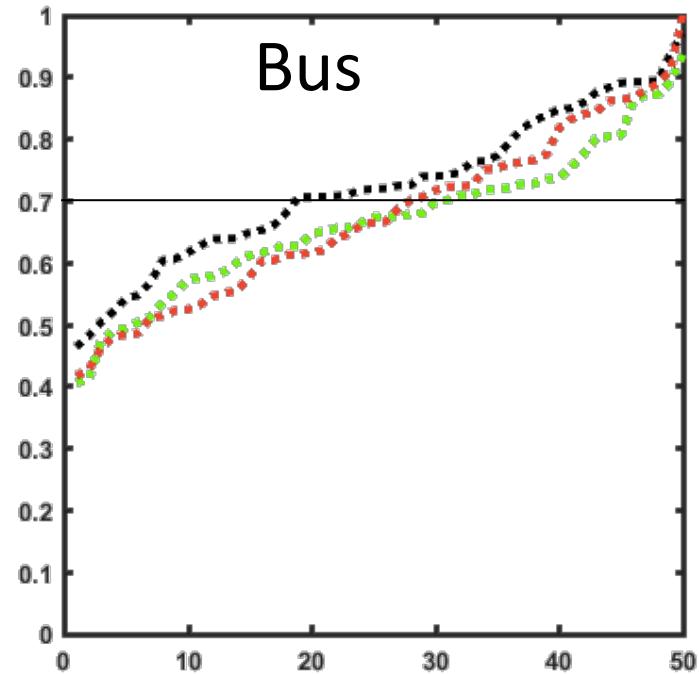
Experimental setup: Features from pre-trained deep network (VGGnet); EdgeBox proposals; ImageNet dataset

		Adversary					
		$\check{y} =$	$\check{y} =$	$\check{y} =$	$\check{y} =$	$\check{y} =$	\dots
Predictor	$\hat{y} =$	$\ell(\text{Forest}, \text{Forest}) + \psi(\text{Forest})$	$\ell(\text{Forest}, \text{Giraffe}) + \psi(\text{Forest})$	$\ell(\text{Forest}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Forest}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Forest}, \text{Giraffe}) + \psi(\text{Giraffe})$	\dots
	$\hat{y} =$	$\ell(\text{Giraffe}, \text{Forest}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	\dots
	$\hat{y} =$	$\ell(\text{Giraffe}, \text{Forest}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	\dots
	$\hat{y} =$	$\ell(\text{Giraffe}, \text{Forest}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	\dots
	$\hat{y} =$	$\ell(\text{Giraffe}, \text{Forest}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Forest})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	$\ell(\text{Giraffe}, \text{Giraffe}) + \psi(\text{Giraffe})$	\dots
	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\ddots

- Prediction game is large (conceptually)
- Efficiently solved using **double oracle method** (McMahan et al. 2003) for constraint generation

Cow





Conclusions

Pessimistic formulation provides benefits:

- In *theory* (**generalization bounds, consistency**)
- In *practice* (**custom losses, active learning**)

Questions:

- Efficiently solve structured predictions games?
- Effective active learning in high dimensions?
- Stronger theory of robust active learning?

Related papers:

- Liu, Ziebart. “*Robust Classification Under Sample Selection Bias.*” NIPS 2014.
- Liu, Reyzin, Ziebart. “*Shift-Pessimistic Active Learning Using Robust Bias-Aware Prediction.*” AAAI 2015.
- Asif, Xing, Behpour, Ziebart. “*Adversarial Cost-Sensitive Classification.*” UAI 2015.
- Wang, Xing, Asif, Ziebart. “*Adversarial Prediction Games for Multivariate Losses.*” NIPS 2015.
- Li, Asif, Wang, Ziebart. “*Adversarial Sequence Tagging.*” IJCAI 2016.
- Chen, Monfort, Liu, Ziebart. “*Robust Covariate Shift Regression.*” AISTATS 2016.
- Fathony, Liu, Asif, Ziebart. “*Adversarial Multiclass Classification: A Risk Minimization Perspective.*” NIPS 2016.



NRI Award #1227495
IIS Award #1526379

